The boundary-layer characteristics and unsteady flow topology of full-scale operational inter-modal freight trains

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Abstract

The boundary layers that develop at the sides of full-scale operational inter-modal freight trains were measured using rakes of 4-hole dynamic-pressure probes. The average boundary-layer displacement thickness at the middle of the trains measured under low crosswind was 1.6 m (within the range of 0.5–3 m), showing turbulence intensities of 4–13%, and length scales of 5–30 m. These characteristics, together with other quantitative details provided in the paper, are intended to provide insight for future experiments and simulations to model real-world conditions around freight trains. The sensitivity of the boundary layer and flow topology to environmental crosswinds and loading configuration was also investigated. In addition, insight is provided into the unsteady flow topology around freight trains, the frequency content of the induced flow, and correlation characteristics.

1 1. Introduction

Inter-modal freight trains in typical operation have lengths of up to 1.6 km, carry a variety of freight container sizes, and travel at up to 110 km/hr. The various container sizes can be double-stacked during transport, as well as carried via different wagon types, resulting in a loading configuration where horizontal gap length and height are variables with a significant range that vary along the length of the train. Efforts are made in practice to optimize the loading configuration for weight distribution and volume efficiency. However, operational conditions also have clear scope for aerodynamic optimization that is not often realised in practice.

The aerodynamics of freight trains are important for the vehicle's overall resistance and, therefore, efficiency. Aerodynamic resistance (drag) can be significantly greater than rolling resistance (Raghunathan et al., 2002, Shetz, 2001). This is primarily due to the steel wheel-rail interface resulting in low rolling resistance and in contrast, the high aerodynamic resistance that arises from the overall make-up of the vehicle; a collection of a number of predominantly bluff components connected in series. In addition, the crosswind stability of a train and its components are a critical aerodynamic characteristic that concerns *Preprint submitted to Journal of Wind Engineering and Industrial Aerodynamics* March 18, 2020

the safety of the operators, as well as nearby civilians and infrastructure. Thus, there has been significant 15 research into the aerodynamics of freight trains, with full-scale experiments (Lai and Barkan, 2005, Lai 16 et al., 2008, Lukaszewicz, 2007, 2009, Gallagher et al., 2018), scaled wind-tunnel experiments (Li et al., 17 2017, Watkins et al., 1992, Engdahl et al., 1986, Gielow and Furlong, 1988, Storms et al., 2008, Peters, 18 1993), scaled moving-model experiments (Soper et al., 2014) and Computational Fluid Dynamic (CFD) 19 simulations (Östh and Krajnovič, 2014, Maleki et al., 2017, 2019, Flynn et al., 2014, 2016, Hemida and 20 Baker, 2010, Gallagher et al., 2018, Paul et al., 2007) having been performed. Such research has established 21 that their exists scope for aerodynamic optimization of these vehicles. Recommendations for improved 22 aerodynamic loading configurations have been made (Li et al., 2017, Lai et al., 2008, Lai and Barkan, 23 2005, Beagles and Fletcher, 2013, Engdahl et al., 1986, Paul et al., 2007), as well as design considerations 24 of containers and wagons (Watkins et al., 1992, Öngüner, Henning, Fey and Wagner, 2020). Further, insight 25 into the flow field around these vehicles (Östh and Krajnovič, 2014, Soper, 2014, Li et al., 2017, Maleki 26 et al., 2017, 2019) have provided insight into the causal mechanisms of the forces experienced. 27

Accommodating the operational length to height ratios (L/H = 250-500) is a significant difficulty in 28 accurately modelling the realistic aerodynamic conditions around a freight train. This difficulty arises from 29 physical limitations in scaled experiments (for example, wind-tunnel test-section length) and computational 30 resource requirements in numerical simulations. This often results in considerably reduced train lengths 31 being modelled (L/H = 10-50). This difficulty and the induced effects have been acknowledged and 32 considered in high-speed train aerodynamic investigations, where comparatively moderate length to height 33 ratios (L/H = 25-100) exist (Muld et al., 2013, Bell et al., 2017, 8-11 December, 2014). Beyond the local 34 flow topology that occurs around the head of the train, (and similarly, prior to the local flow around the tail), 35 a boundary layer develops over the surface of the vehicle. The developing boundary layer is characterised 36 by the velocity, turbulence and length-scale profiles. 37

The aerodynamic characteristics of bluff bodies and their geometric features in general have been well 38 established to be sensitive to the turbulent conditions they are exposed to (Cooper and Campbell, 1981, 39 Watkins and Cooper, 2007). In wind engineering, accurate modelling of the velocity, turbulence and 40 length-scale atmospheric boundary-layer characteristics that a building is exposed to is critical for ensuring 41 accurate prediction of wind loads (Holmes, 2001). Similarly, there have been recent efforts to charac-42 terise (Wordley and Saunders, 2008, McAuliffe et al., 2014) real-world on-road turbulence and replicate 43 these conditions in wind-tunnel and CFD simulations for automotive aerodynamic investigations (Sims-44 Williams, 2011). Specifically, the aerodynamic sensitivity of a freight container to the conditions it is 45 exposed to has been indicated by a number of investigations. A container in isolation has been shown to 46

experience a significantly different flow field, pressure distribution and forces to a container located within a series of containers (Östh and Krajnovič, 2014, Li et al., 2017, Maleki et al., 2017, 2019). Further, the drag of individual containers have reportedly been found to be dependent on location in the train, only becoming consistent at approximately 8 cars from the nose (Gielow and Furlong, 1988, Engdahl et al., 1986). Thus, there is clear motivation to accurately represent the flow that a shipping container is exposed to, in order to ensure that the findings from investigations aiming for optimization are correct in their magnitude and overall effect.

A common method in investigations that consider the effect that model length can have on aerodynamic 54 findings, is to model an arbitrary region within the length of the train, representative of the conditions that 55 the majority of containers experience (Östh and Krajnovič, 2014, Li et al., 2017, Maleki et al., 2017, 2019). 56 However, the characteristics at this arbitrary *middle* position, until now, have not been defined for opera-57 tional freight trains subject to real-world atmospheric conditions. Some insight into these characteristics 58 has been limited to slipstream-motivated experimental campaigns, which are focussed on accurately mea-59 suring the peak induced-velocity caused by trains at a specific position in their immediate vicinity (3m from 60 the track centre); where waiting passengers, workers or infrastructure can be most strongly affected. With 61 safety as a motivation, and the resulting European regulations for testing and requirements that must be met 62 for trains to operate (CEN, 2013), there has been a wide range of research in the area (Sterling et al., 2008, 63 Soper et al., 2014, Muld et al., 2013, Flynn et al., 2014, 2016, Bell et al., 8-11 December, 2014, 2016b, 64 2017, Soper and Baker, 2019). However, such research and regulations are not intended to, and therefore 65 do not properly measure and resolve a train's boundary-layer characteristics. 66

With further insight into the boundary layer characteristics of operational freight trains, models in future investigations could be tuned to match realistic oncoming conditions in the same manner as for the atmospheric boundary layer in the practice of wind engineering. Experimentally, this could be achieved through boundary-layer augmentation utilizing roughness, tripping and vortex-generating elements (Irwin, 1981, Bell et al., 8-11 December, 2014, Sima et al., 2016, Buhr and Ehrenfried, 2017, Bell et al., 2017). Similar approaches could be applied numerically, or alternatively, through advanced recycling techniques (Östh and Krajnovič, 2014) or through tuning of inlet conditions.

In this work, the characteristics of boundary layers of operational inter-modal freight trains are presented. Here we use the terminology *boundary layer* in a broad sense to describe the induced flow along the side of the train and tracks. It may be a combination of turbulent structures generated along the side of the train, and, in the presence of cross-wind, wake structures over the side of the train. Measurements were made with 3 horizontal boundary-layer rakes perpendicular to the rail to measure the side boundary-layer.



Figure 1: An operational full-scale inter-modal freight train driving past measurement rakes of 4-hole dynamic pressure probes, placed either side of the train.

⁷⁹ Each rake contained 7 four-hole dynamic pressure probes. A vertical rake of 3 probes was also utilized
to investigate the boundary layer's three-dimensionality. In addition to quantifying the boundary layers,
⁸¹ insight into the flow physics around inter-modal shipping containers and their loading configurations is
⁸² presented.

Measurements of six inter-modal freight trains were performed, each effectively measured three times 83 by each of the horizontal rakes. Inter-modal freight trains have no standard, consistent configuration. 84 Therefore, each train had different loading configurations and further, operated within different environ-85 mental conditions. It is acknowledged this is a small sample size that does not result in a statistically 86 significant description of a benchmark-type boundary-layer for a specific train. However, these measure-87 ments - for the first time - enable the boundary layer characteristics representative of real, inter-modal 88 freight trains operating in real conditions to be described. These results provide valuable insight into real-89 world operational conditions and hence can be used to help inform setting up wind-tunnel experiments 90 and numerical simulations that investigate the aerodynamics of freight trains. This work is part of a col-91 laboration with Pacific National — a freight transport provider — with the ultimate aim of improving the 92 aerodynamic efficiency of inter-modal freight transport 93

94 2. Methodology

95 2.1. Test site

The experiment was performed at Wingeel, Victoria, Australia. The standard-gauge track network that inter-modal freight trains operated within proximity to Melbourne was assessed for aerodynamic and logistical considerations. The Wingeel test site was identified as suitable, utilizing Pacific Nationals expertise as a transport operators. The test site consisted (Fig. 1) of a single track, which allowed access and simultaneous measurement along both sides of the train without having to consider rail traffic on a parallel track. Trains operate at full operational speed ($u_t \approx 110$ km/hr) and were given prior notice of the experiment and infrastructure setup to maintain the maximum speed during passage past the data collection infrastructure. The track is relatively straight (Fig. 2), which enabled a straight vehicle passing the measurement equipment to operate at maximum speed.

A minor highway was located approximately 1 km north of the test site. At this distance, the effect of passing automotive vehicles on the measurements was expected to be negligible. A minor local road crossed the railway 50 m east of the test site and contained minimal traffic infrastructure (lights/sirens) mounted on poles. This road experienced minimal traffic, and vehicles if present were stationary and ≈ 10 m from the track during measurements of the trains. This configuration is not expected to have significantly shielded the measurement devices from the induced flow of the trains being measured, and thus not expected to have a significant influence on the results.

The local topography was relatively flat, and clear of trees and vegetation. Minimal local topography was desired, to best represent the ideal conditions of the rail vehicle operating in open air. This of course opened the site and vehicle to be exposed to ambient wind, however, those conditions were measured.



Figure 2: The experiment test site at Wingeel, Victoria, Australia. A large-scale view of the track and roads are illustrated (top), with the local topography and location of trees and vegetation illustrated in the zoomed-in figure inset below.

116 2.2. Test vehicles & conditions

The passing of inter-model freight trains in normal operation were recorded in the experiment. Only 117 single-stacked shipping containers existed on the trains subject to measurement. A variety of loading 118 configurations, in terms of gap sizes between containers, existed within each train measured, and indeed 119 between all trains in the set. In Figure 3, the extent of gap variation is visible. Figure 3a illustrates how 120 containers can be positioned with no gap between them when loaded on the same wagon. Also in Figure 3a, 121 a small gap is visible that is required when containers are loaded on sequential wagons, due to the distance 122 required by the coupling between wagons which also provides the ability for the train to operate through 123 curves. In Figure 3b, a 'fractional' gap is visible. These occur due to the mismatch between available 124 space on the wagon for loading, and the size of the container(s) loaded onto this space (referred to as slot 125 utilization). In Figures 3c and d, gaps in the order of a full sized container or larger are visible. These occur 126 as it is common practice for sets (typically of 5) of multiple wagons to be grouped and moved together. 127 When these groups are loaded and added to make a full train, such gaps can exist due to un-required or 128 unsuitable space on the wagon for more containers. 129

In this experiment, 6 inter-modal trains were measured. The train number, loading configuration description (quantified loading configuration is presented in Section 3.2), and test conditions: train speed u_t , ambient wind speed, u_a , absolute ambient-wind yaw-angle γ , and relative ambient-wind yaw-angle β (both angles being around the z-axis), are presented in Table 1. The effects of these characteristics are discussed in the results section.

	Table 1: Test Test Vehicles	Vehicles and Test Conditions Test Conditions			
No.	Gap Sizes	$u_t^1 \; (m/s)$	$u_a^1 \; (m/s)$	γ (°)	β (°)
T1	Small-Very Large	30.7	2.3	-4	-0.3
T2	Small-Medium	32.7	3.0	20	2.0
T3	Small-Large	31.1	4.0	12	1.8
T4	Small-Medium	29.9	4.4	149	3.9
T5	Medium-Very Large	24.5	5.0	-48	-9.9
T6	Small-Medium	26.1	7.0	-137	-8.7

35 2.3. Setup

135

The measurement equipment was arranged at the Wingeel site and measurements were obtained as the trains passed by them as presented in Fig 1. The experimental setup of the measurement equipment and data acquisition is illustrated in Figure 4, with photos of the setup and specific equipment provided in Figure 5.

The primary pieces of measurement equipment were 4-hole dynamic-pressure probes, positioned in 140 three rakes (R1, R2 & R4 in Fig. 4) of 7 probes, arranged perpendicular to the path of the trains. The probe 141 nearest to the train was located 2.5 m from the nearest rail, which corresponds to y = 1.71 m from the 142 surface of a shipping container travelling on a wagon on the rail. The subsequent probes were positioned at 143 $\Delta y = 1$ m increments in the horizontal direction. The probes were positioned z = 2.1 m above the top of 144 rail, which corresponds to approximately half the container height. This setup was consistent for all three 145 rakes, where rakes R1 & R2 were positioned at the same distance along the track, on either side (Fig 5(a) 146 in order to provide insight into the correlation and coherence of the flow around the trains. Rake R4 was 147 positioned on the same side as R1, $\Delta x = 30$ m away. 148

Rake R3 contained 4 horizontal probes positioned in the manner described above, with 3 probes positioned in the vertical direction at $\Delta z = 0.5$ m increments, instead of the furthest 3 horizontal positions (Fig 5(c). These were positioned to gain insight into the vertical velocity gradient of the boundary layers.

Inside each equipment case were 32 channel Data Acquisition (DAQ) cards that were connected over the large distances to a laptop via Ethernet cables. Data was acquired at a sampling frequency of 1000 Hz, with sampling times of approximately 140 seconds. Power was supplied to the DAQ and measurement equipment by a battery. A laptop and the battery were charged using a portable generator; however, during actual measurement times they were disconnected from the generator and ran solely on battery power, to remove the possible effect of electrical noise caused by the generator.

The event of a train passing, and the position relative to the train nose were measured using two infra-158 red transmitter/receivers mounted on vertical supports of the 4-hole probes closest to the rail in rakes R1 159 and R3 (Fig 5(d). On the opposite side of the track was a reflective square element that reflected the 160 transmitted infra-red light to the receiver (Fig 5(e). When the path (illustrated in Fig 4(a) as red lines) 161 was broken, a voltage change was measured in additional DAQ cards, thus each unit and reflector will be 162 subsequently referred to as a 'light gate'. The primary purpose of this equipment was to measure the train 163 speed. However, these devices also provided insight into the loading configuration, as the light path was 164 positioned at the height of the shipping containers, thus gaps between containers were recorded. 165

The ambient wind magnitude, u_a , and direction and temperature were measured at a 100Hz sampling rate by a weather station with an ultra-sonic anemometer. This was located on the vertical support of the probe furthest from the track in rake R1 (Fig 5(a)).





b. Freight - Fractional Gaps



c. Freight - Container Gaps



d. Freight - Multiple Container Gaps



Figure 3: Variety of gap sizes between shipping containers observed on the different operational freight trains.



Figure 4: Experimental setup: rakes (R1-R4) of 4-hole dynamic-pressure probes (P1-P7), light-gates (LG1-2) and light-beam paths (red), processing area (CPU) and data acquisition and measurement equipment boxes (blue) presented in (a). isometric, (b): top down, and (c): front-on perspectives.



Figure 5: Photos of the setup and experimental equipment. (a): rakes R1 and R2, probe support infrastructure and data acquisition boxes, (b): rake of probes, (c): vertical rake R3, (d): light-gate transmitter/receiver and (e): reflective element for light-gate.

169 2.3.1. Flow velocity

The velocity induced by the train's movement was measured by 4-hole dynamic-pressure probes. These were designed, manufactured and calibrated by the *Monash University Wind Tunnel Platform*, and have previously been used – and the results published – in a scaled wind-tunnel experiment investigating the unsteady wake of high-speed trains (Bell et al., 2016*a*). The 100 mm long probes were positioned $\Delta y =$ 200 mm away from the primary vertical support and mounted in 14 mm diameter horizontal cylinders to reduce the interference the probe mounting could have on measurements. The mounting configuration of the probes is visible in Fig 5(b).

The probes have a cone of acceptance of $\pm 45^{\circ}$, and therefore were rotated to face the direction of the 177 oncoming train (facing opposite to the direction the trains were travelling) in order to measure the flow 178 induced by the trains' surfaces. The probes have an accuracy of approximately ± 1 m/s and $\pm 1^{\circ}$. Flow that 179 was beyond the cone of acceptance (< 5%) was identified in processing through inspection of the pressure 180 magnitude, sign, and pressure relative to the other holes on the probe. The pressure of each hole was 181 measured with a differential pressure transducer referenced to atmospheric pressure. Atmospheric pressure 182 was measured by a reference port connected to a plenum shielded in a container with small vents (to allow 183 ambient pressure to exist within the container) located at each rake, within a protective equipment case that 184 was also vented to the atmosphere. 185

Within each equipment case, located at each rake (see blue boxes in Fig 4), was a 32 channel *Dynamic Pressure Measurement System* (DPMS). Each hole of each probe was connected to a transducer in the DPMS by 4 m of 1.2 mm internal diameter Poly-Vinyl-Chloride (PVC) tubing.

The phase and amplitude of the pressure measured by the transducer is subject to distortion relative to the true pressure at the desired measurement point. This distortion occurs due to resonant characteristics of the system (Iberall, 1950). The amplitude and phase response for each measurement was corrected using the inverse transfer function (ITF) method (Irwin et al., 1979). The frequency response of the pressure measurement system was determined theoretically using a method outlined by Bergh and Tijdeman (1965). The system had no peak frequencies, and fell below an amplitude of 0.2 at 60 Hz. Beyond this frequency correction was not applied, in order to reduce the chance of noise amplification.

Dynamic-pressure probes were utilized instead of ultra-sonic anemometers - more commonly used in slipstream motivated investigations (Sterling et al., 2008) – initially due to cost and availability. More importantly, the use of a large number of probes resulted in a spatial resolution able to reasonably resolve the boundary layer, take simultaneous measurements either side of the track, and at different longitudinal locations – effectively measuring the passing of the same train 3 times.

201 2.3.2. Train velocity & position

As the two light gates were positioned 30 m from each other in rakes R1 and R4, the difference in time (Δt) between the two light gates of the increase/decrease caused by the the train's nose and tail passing in the output voltage signal was used to determine the train speed.

An example of the voltage signals of both light-gates is presented in Figure 6(a). Here, the events of the step-up caused by the nose passing, and subsequent step-down as the tail moves past, are visible, as is light-gate 1 signal, clearly lagging light-gate 2 (the train was travelling West in this example). Figure 6(b) shows the voltage of the pressure transducer from the probes closest to the track within each rake. Again, the lag of the head-pressure pulse is clearly visible due to the spatial offset of the probes location. The train velocity was calculated by

$$u_t = \frac{x_{LG_1} - x_{LG_2}}{t_{LG_1} - t_{LG_2}},\tag{1}$$

where the longitudinal position of light gates LG_1 and LG_2 , x_{LG_1,LG_2} were set and thus known in the experimental setup, and the times when the train nose passes LG_1 and LG_2 , t_{LG_1,LG_2} , were determined from the light-gate measurements.

The train velocity was calculated twice for each passage, using the nose and tail passing events separately. This enabled the acceleration to be calculated. In all cases, the train acceleration was minimal $(a_t < 0.1 \text{ m/s}^2)$, likely due the minimal separation distance between the light-gates relative to the scale of the train and track. As such the train speed u_t was simply taken as the speed calculated from the nose passing, without acceleration being considered. This train speed was used to convert the data from the temporal to the spatial domain. All data was then re-sampled to a common spatial resolution, and aligned relative to the train nose (x = 0).

221 2.3.3. Flow visualisation

Additional insight into the induced flow field as the trains moved through the test site was achieved with high-visibility yellow wool-tufts. The wool tufts were fixed to the vertical support structures in rake R1, at each spanwise probe position and at multiple heights. It was expected they influenced by the support geometry to a degree. However, the tufts are able to indicate flow in all horizontal directions (they don't have a limited cone of acceptance angle as the pressure probes do), thus they provide complimentary qualitative results.

Photos of the wool tufts were obtained with a digital single-lens-reflex (DSLR) *Canon 60D* camera, with a focal length of 18 mm, f-stop of f/5.6, exposure time of 1/500 seconds, and frame rate of 4 Hz.



Figure 6: (a): Normalised voltage signal from light-gates LG1 and LG2. (b): Normalised pressure signals from the centre hole (H_0) of each of the probes closest to the train (P1) within each rake (R1-R4).

230 3. Results

The results of an individual train are presented first, to provide initial insight into the measurements obtained and the processing techniques applied. The boundary layer characteristics of all trains are then presented and compared, followed by the specification of a 'characteristic boundary layer', representative of an average train operating under minimal crosswind. Finally, insight into global and local flow features are presented through flow mapping, frequency and correlation analysis.

236 3.1. Velocity profiles

237 3.1.1. Horizontal arrays

In this experiment, the flow induced by the train's movement is measured, thus induced velocity is highest, closest to the surface. The longitudinal velocity (*u*) measured by each of the 7 probes in the horizontal rake, R1, for train T3, is shown in Figure 7. These results are representative of the trains (T1, T2, T3) measured with low crosswind; $u_a < 4$ m/s (relative yaw angle, $\beta < 2^\circ$). The differences between the velocity measured at the different rakes (R1, R2, R4) are presented and discussed in the following sections. The velocity was filtered with a 1 second moving-average window for clarity.

The boundary layers around the freight trains are not simply two-dimensional, indeed, nor are they necessarily boundary layers in the purest sense. However, they are analysed here as 2D boundary layers here for simplicity, as previous researchers have done (Muld et al., 2013, Baker, 2010, Bell et al., 2015). Thus, the longitudinal velocity (*u*) is of primary focus as it contributes most significantly to boundary layer flow (in this case also). The other velocity components are analysed in Section 3.3. Further, the flow is characterised in later sections with 2D boundary-layer parameters such as displacement thickness and shape factor. This enables a level of quantification of boundary layer thickness, and a method for comparison across different cases.

These results clearly show the existence and increasing thickness of the induced boundary layer along the length of the train. This is evident in the velocity being higher at positions close to the train (e.g. y = 1.71 m) than at positions further away from the train (e.g. y = 7.71 m). Furthermore, it can be seen that these induced velocities tend to increase along the length of the train. Significant fluctuations in velocity within the boundary layer are largely consistent across the horizontal positions measured. In addition, a visible lag in the longitudinal direction exists for the probes further away from the train, caused by the flow disturbance requiring time to convect/diffuse to these positions.

These results are consistent with research into the slipstream of freight trains by Soper et al. (2014), Soper (2014), Sterling et al. (2008) which have also observed increasing induced velocity that reaches a maximum along the body – due to the boundary-layer thickness increasing – followed by the significant reduction of induced velocity after the tail. This is in contrast to the slipstream of high-speed trains which also exhibit increasing velocity along the length due to the boundary-layer thickness increasing, however, the highest velocities are found in the near-wake region (Bell et al., 2017, Sterling et al., 2008).



Figure 7: Longitudinal induced velocity, u, normalised by train speed u_t measured by each probe in rake R1 for train T3. Dotted vertical lines indicate train nose and tail.

265 3.1.2. Vertical array

In contrast to the horizontal development of the boundary layer, trends in velocity profile in the vertical direction are not as clear. The longitudinal velocity (*u*), measured by each of the 4 probes at a distance of y = 1.71 m from the train, in the vertical rake, R3, again for train T3, are presented in Figure 8. In general, at this position, the velocity is higher at the lower measured positions (z = 0.6 m), closer to the ground, than the higher positions (z = 2.1 m). This indicates that the boundary layer is thicker closer to the ground. Such a result is expected, and similar findings have been observed in the literature (Soper et al., 2014). This is proposed to be due to the presence of additional elements of the train such as the wheels, bogies, and the coupling mechanisms of the wagons. Such elements are likely to increase the entrainment of the ambient flow. It is unclear how the ground plane affects the velocity closer to the ground and further away laterally from the train, as the lowest measurement was approximately 1.1 metres above the local ground surface.

Interestingly, this trend of increasing velocity with increasing height is occasionally inverted, most notably at x = 750m in Figure 8. At this point, velocity is highest away from the ground, and decreases towards it. There are clear signs of correlation in the velocity fluctuations between the vertically separated probes, but perhaps weaker than in the horizontal direction. Together with the inversion of the velocity gradient this indicates the existence of large-scale, three-dimensional, coherent structures within the boundary layer.



Figure 8: Longitudinal induced velocity, u, normalised by train speed, u_t , measured by each probe in the vertical rake R3 for train T3. Dotted vertical lines indicate train nose and tail.

282 3.1.3. Horizontal boundary layer profiles

Boundary layer profiles at discrete positions along the train are presented in Figure 9. These are de-283 veloped from the same velocity measurements by each of the 7 probes in the horizontal rake, R1, for train 284 T3. In this case, the results are presented simply to demonstrate the boundary layer velocity profile. Each 285 sequential instantaneous discrete position was selected to illustrate the boundary layer growth along the 286 train's length. Significant variation in these instantaneous profiles existed at different locations for the dif-287 ferent trains, as can be expected from the transient velocity profiles in Fig. 7. The boundary layer profile at 288 each spatial increment was developed, in order to calculate boundary layer characteristics along the train's 289 length. The corresponding characteristics are analysed and the differences between different rakes and 290 trains are presented below. 291



Figure 9: Boundary layer velocity profiles determined from each of the 7 probes in rake R1 at different discrete longitudinal positions along the train.

292 3.2. Boundary-layer characteristics

The characteristics of the boundary layers for each of the 6 trains – low wind, and crosswind exposed trains – are presented and analysed in this section. Following this, a characteristic boundary layer is described, representative of a typical developed boundary layer around an inter-modal freight train. This is intended to help inform setting up experiments and numerical simulations intending to model real-world conditions.

298 3.2.1. Displacement thickness & shape factor

Utilizing the boundary layer velocity profiles presented above, the displacement thickness was calculated using

$$\delta^*(x) = \int_0^\infty (1 - \frac{u}{u_t}) dy.$$
 (2)

In Figure 10, the displacement thickness for trains (T1, T2, T3) with low crosswind (relative yaw angle, $\beta < 2^{\circ}$) are presented. Results from each individual rake (R1, R2, R4) are presented, as well as the ensemble average of all three.

For all three trains, the boundary layer thickness initially increases quickly up to $\delta^* \approx 1$ m over the first ≈ 200 m. Following this, a further, slower development is evident up to a common range of $\delta^* = 1-2$ m, within the full range of $\delta^* = 0.5-3.5$ m. These values are higher than the range of $\delta^* = 0.6-1.4$ m estimated by Soper (2014) in a 1:25 scale moving-model freight-train experiment and $\delta^* \approx 0.1 - 0.3$ m measured by both Li et al. (2017) in a 1:14.6 scale freight-train wind-tunnel experiment and by Maleki et al. (2017) numerically. Further, these values are an order of magnitude higher than full-scale, operational *high-speed train* boundary layers estimated by Sterling et al. (2008) of $\delta^* = 0.1-0.4$ m.

Relative differences between the measurements from the three rakes are also visible in Figure 10. In

particular, R1 and R4, positioned on the same side of the train exhibit very similar calculated displacement 312 thickness, in contrast to that of R2, positioned on the other side of the train. A possible explanation for 313 this, is the influence of the albeit minor crosswind, as the loading configuration is symmetric, and would 314 be expected to influence both sides equally. It is for this reason that results from all three rakes are used 315 to calculate the ensemble average. Even though it is likely that the measurements from rakes R1 and 316 R2 are not independent from each other, as they are positioned at the same longitudinal position. The 317 measurements from rake R2 were used in the calculation of averages, to include these differences to better 318 represent the 'average' boundary layer of the trains measured. 319

The loading configuration of each train is expected to have an influence on the boundary layer that develops. In an attempt to quantify the loading configuration along the trains length – in order to compare directly the boundary layer displacement thickness – a cumulative blockage parameter was developed. This cumulative blockage at each spatial measurement increment, i, was calculated as

$$x_{B_i} = x_{B_{i-1}} + x_{blocked,i},\tag{3}$$

using the light-gate measurements, where $x_{blocked,i} = 1$ when the light-gate measured a path blocked by a container, or $x_{blocked,i} = -1$ when the light-gate path was not blocked, thus a gap existed. This parameter enables consecutive gaps, or conversely, containers packed closely together, to be visualised.

Profiles of cumulative blockage for trains T1, T2, T3 are presented in Figure 11. Comparison of this 327 parameter to the corresponding train displacement thickness in Figure 10 shows that the relative changing 328 cumulative blockage between the trains tends to match the relative displacement thickness; higher blockage 329 (less gaps) approximately corresponds to a thicker boundary layer. Train T1 consistently has the lowest 330 displacement thickness and cumulative blockage (the shallower gradient indicates it has small, consistent 331 gaps) relative to trains T2 and T3. Further, T2 initially has a large displacement thickness and slightly larger 332 cumulative blockage; however, from $x \approx 600$ m, its blockage and displacement thickness both decrease, 333 beyond which both remain lower than T3. Such results indicate loading configuration has an impact on 334 the boundary layer, as one could expect; without the effect of crosswind, the boundary layer would be 335 expected to increase along the length of the vehicle, sufficiently small gaps could have minor effect or act 336 as 'roughness', while larger enough gaps would lead to separation of the flow that results in the boundary 337 layer re-starting. 338

339 The shape factor is defined by

$$H(x) = \frac{\delta^*(x)}{\theta(x)},\tag{4}$$

340 where

$$\theta(x) = \int_0^\infty \frac{u}{u_t} (1 - \frac{u}{u_t}) dy,\tag{5}$$

is the momentum thickness. This provides an indication of the form of the boundary layer profile. Profiles of the shape factor are presented in Figure 12 for the three trains T1, T2, T3. No clear trends exist for the shape factor over the train lengths, indicating that the boundary layer form is relatively constant. The shape factor of $H \approx 1.4$ indicates the boundary layer is turbulent, as expected.

The displacement thicknesses of the trains with higher crosswinds: T4 ($\beta = 4^{\circ}$), T5 ($\beta = 10^{\circ}$), T6 ($\beta = -9^{\circ}$), are presented in Figure 13. In this case, the results from the different rakes R1 and R2 are designated as leeward, (LW), and windward (WW) relative to the crosswind direction.

Significant differences are immediately evident with the leeward and windward boundary layers. The crosswind essentially pushes the boundary layer towards the surface on the windward side, to the point where the probes are unable to measure a boundary layer. On the leeward side, the calculated displacement thickness is significantly larger than that observed for the trains with no/little crosswind: $\delta^*_{LW:T4,T5,T6} =$ 2–4 m, compared to $\delta^*_{T1,T2,T3} = 1-2.5$ m, respectively. However, complex, three-dimensional flow is expected on the leeward side, not a simple structureless boundary layer, in which case the calculation of the displacement thickness is not entirely meaningful.



Figure 10: Displacement thickness, δ^* , profiles for each train (T1,T2,T3) with relatively low crosswinds ($\beta < 2^\circ$). An ensemble average, as well as individual rake profiles are presented for each train. Dotted lines indicate the location of the train noses and respective tails.



Figure 11: Cumulative blockage profiles of trains T1, T2 &, T3.



Figure 13: Displacement thickness, δ^* , profiles for each train (T49T5,T6) with relatively high crosswinds ($\beta > 2^\circ$). An ensemble average, as well as individual rake profiles are presented for each train. Dotted lines indicate the location of the train noses and respective tails.

355 3.2.2. Turbulence characterisation

The flow that the measurement probes are exposed to as the trains pass is statistically non-stationary. Single events such as the nose/tail passing and unique gaps configurations, result in a flow that changes over time, rather than fluctuates around a consistent mean (a statistically stationary flow). Thus, the typical description of turbulence, quantified by turbulence intensity:

$$I_{u} = \frac{\sigma_{u}}{(u_{t} - \bar{u})}, \quad I_{v} = \frac{\sigma_{v}}{(u_{t} - \bar{u})}, \quad I_{w} = \frac{\sigma_{w}}{(u_{t} - \bar{u})}, \quad (6)$$

where $\sigma_{u,v,w}$ and \bar{u} are calculated over an entire statistically stationary signal, is not applicable here.

In order to provide an indication of the turbulence within the boundary layer of full-scale freight trains, 361 turbulence intensity along the train length is calculated over a moving window of filtered data. A single-362 pole Butterworth, 0.03-100 Hz band-pass filter was applied to the velocity measurements. The cut-off 363 limits correspond respectively to a spatial length of less than the train lengths (0.03 Hz corresponds to 364 ≈ 1000 m), and of the upper limit of the measurement system's frequency response. In Figure 14, the 365 effect of the filtering of an example velocity time-series is illustrated, with the filtered result resembling a 366 stationary signal. Regardless, a 5 s moving window was used to calculate the turbulence intensity over the 367 length of the train: 368

$$I_u(x) = \frac{\sigma_u(x)}{(u_t - \bar{u}(x))}, \quad I_v(x) = \frac{\sigma_v(x)}{(u_t - \bar{u}(x))}, \quad I_w(x) = \frac{\sigma_w(x)}{(u_t - \bar{u}(x))}, \tag{7}$$

where $\sigma_{u,v,w}(x)$ and $\bar{u}(x)$ are calculated over a moving window equivalent to five seconds ($x \approx 150m$) along the train length.

The longitudinal turbulence intensity, $I_u(x)$, calculated using equation 7, measured by each of the 7 371 probes in the horizontal rake, R1, for train T3, is shown in Figure 15. These results are again representative 372 of the trains [T1, T2, T3] measured with low crosswind; $u_a < 4$ m/s (relative yaw angle, $\beta < 2^{\circ}$). 373 Turbulence intensities of 10-30% were measured, highest closest to the train, that increases along the length 374 as the boundary layer thickness increases. These levels of turbulence are similar to the analogous case of 375 on-road turbulence – what an automotive vehicle (of similar velocity and scale as shipping containers) 376 experiences when operating on the road, including the effect of the environment and other vehicles -377 characterised by Wordley and Saunders (2008) and McAuliffe et al. (2014) who found turbulence intensities 378 of $I_u = 2-16\%$. In spite of the 5 second moving window over which the turbulence was calculated over, 379 the profiles show significant fluctuation in turbulence along the length. This demonstrates specific loading 380 configurations or local wind events (for example at x = 800 m), can have a significant impact on the 381

³⁸² boundary layer characteristics beyond the velocity profile.

In Figure 16, the different components of turbulence intensity, I_u , I_v , I_w , are presented for probe 383 P1, in rake R1, for train T3. The anisotropic characteristics of the turbulence are relatively consistent: 384 $I_u: I_v: I_w \approx 1: 0.4: 0.6$, as the turbulence generally increases, with additional fluctuations along the 385 train length. Interestingly, greater turbulence exists in the vertical direction than the horizontal. This is 386 contrary to that generally found on roads by Wordley and Saunders (2008), who determined anisotropic 387 ratios of $I_u: I_v: I_w \approx 1: 1: 0.6$, where the proximity to the ground is expected to reduce the level of 388 velocity fluctuations. A potential explanation for this difference is that in these experiments, measurements 389 were made specifically next to the vehicle, in contrast to general exposure to the effects of a number of 390 vehicles and infrastructure characterised on-road. 391

The turbulence intensities, I_u and $I_{u,v,w}$, calculated using equation 6 over the middle 40% of the train, are presented on the vertical axis as points in their respective colours for all probes in Figure 15. This shows the different components of the closest probe in Figure 16, respectively. The middle 40% was calculated as the section of train where $x = 0.3L_t : 0.7L_t$, where L_t is the length of each train and was selected to exclude the effect of the nose and tail flow regions, to best represent a representative, if somewhat arbitrary, middle section of a freight train.



Figure 14: Normalised longitudinal velocity of P1, T1 with a 100 Hz low-pass and 0.03–100 Hz band-pass single-pole Butterworth filter applied, used to calculate turbulence intensity.



Figure 15: Longitudinal turbulence intensity I_u profile along the train T3, calculated over a 5 s moving window at each probe in rake R1. Average of the middle 40% of the train presented as corresponding coloured points on the vertical axis.



Figure 16: Profiles of the different components of turbulence intensity I_u , I_v , I_w along train T3, at probe P1, in rake R1. Average of the middle 40% of the train presented as corresponding coloured points on the vertical axis.

398 3.2.3. Characteristic boundary layer

The boundary-layer characteristics measured by all three horizontal rakes (R1, R2, R3) for the middle 400 40% section of the three trains measured with low crosswind (T1, T2, T3) ($u_a < 4$ m/s, relative yaw angle 401 $\beta < 2^{\circ}$) have been averaged and are presented graphically in Figure 17 and tabulated in Table 2. These 402 results are intended to be a reference for future investigations intending to model (or compare to) realistic 403 boundary-layer characteristics experienced by an intermodel freight train. The corresponding standard 404 deviation of each of the average characteristics are also presented at the bottom of Table 2 to provide an 405 indication of the variability from the different rakes and trains measured.

The velocity, turbulence intensity and length-scale profiles of the characteristic boundary-layer are presented in Figure 17(a), (b) and (c), respectively. Included in Figure 17a, are the displacement thickness (δ^*) and momentum thickness (θ) , based on the calculated average velocity profile. The boundary layer thickness (δ_{99}) was estimated from where $u \approx 99\%$ of the 'freestream' velocity, from a simple power-law model of the velocity profile:

$$u = u_{ref} \left(\frac{y}{y_{\rm ref}}\right)^{\alpha},\tag{8}$$

where $\alpha = 0.25$ and u_{ref} was the measured velocity at $y_{ref} = 1.71$ m. These values are also provided in Table 3.

The anisotropic characteristics of the turbulence identified above for train T3, are the same in this characteristic boundary layer; $I_u : I_v : I_w \approx 1 : 0.4 : 0.6$, and remain consistent across the boundary layer thickness.

The length scales presented in Figure 17(c) were estimated by least-squares fitting of the Kármán spectra to the velocity measurements with the same single-pole Butterworth, 0.03–100 Hz band-pass filter described above, for the middle 40% section of each train. These results are again similar to on-road turbulence length scales of $L_{u,v,w} = 2-10$ m (Wordley and Saunders, 2008, McAuliffe et al., 2014).



Figure 17: Characteristic boundary-layer properties: (a) Velocity (mean velocity, estimated boundary layer thickness, displacement thickness and momentum thickness), (b) turbulence, and (c) length-scale profiles.

<i>y</i> (m)	$1-u/u_t$	I_u (%)	I_v (%)	I_w (%)	L_u (m)	L_v (m)	L_w (m)
1.71	0.65	13.6	5.4	7.9	25.4	4.5	5.7
2.71	0.72	12.0	4.8	7.0	27.2	5.7	6.2
3.71	0.77	11.1	4.4	6.5	29.7	6.7	7.6
4.71	0.81	10.5	4.1	6.1	30.9	7.3	8.4
5.71	0.87	9.9	3.9	5.8	31.8	7.4	8.1
6.71	0.89	9.3	3.9	5.7	31.7	6.6	8.4
7.71	0.93	9.3	3.7	5.5	32.8	6.6	6.9
σ	0.08	1.7	0.5	0.8	9.5	2.4	2.4

Table 2: Characteristic boundary-layer properties for the low crosswind cases (T1, T2, T3).

Table 3: Boundary layer thickness characteristics for the low crosswind cases (T1, T2, T3). δ_{99} (m) δ^* (m) θ (m) H

0 ₉₉ (m)	0* (m)	θ (m)	Н
9.9	1.6	1.2	1.34

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420 3.3. Flow topology

The flow topologies around each of the freight trains are presented in two-dimensional planes in this section, complimented by wool-tuft flow visualisations. The three components of velocity, u,v,w, measured simultaneously by each probe using rakes R1 and R2, and for all trains, are presented in Figures 18, 19, and 20, respectively. Note that in these and subsequent 2D spatial figures, the *x* and *y* axes are not presented with a true 1:1 scaling, in order to more easily interpret the data. These results enable further insight into the cause of the development and significant fluctuations in boundary-layer thickness along the length of the trains, and difference between each side of each train.

428 3.3.1. Global topology

Clearly visible in Figure 18 is the significant difference in the u velocity for the trains with low cross-429 wind (T1, T2, T3) to the trains experiencing higher crosswinds (T4, T5, T6). Even for the trains under low 430 crosswind, the flow around the train is asymmetric, which is unlikely to be caused by the predominantly 431 symmetric loading configurations. This is clearer for T2 and T3, where a thicker region of induced flow on 432 the positive y side of the trains – consistent with the positive $\beta \approx 2^{\circ}$ ambient wind for both trains. Here, 433 the (albeit low-level) crosswind effectively pushes the boundary layer towards the train surface, reducing 434 its thickness on the windward side and increasing the level of induced flow on the leeward side to a peak 435 of $0.6u_t$. This is seen to a significantly greater extent for the high crosswind trains (T4, T5, T6), where the 436 boundary layer is reduced beyond the measurement points on the windward side, and the induced velocities 437 increase to a level of up to $0.8u_t$ on the leeward side. 438

Regardless of the observable influence of the low-cross wind on the flow topology, trains T2 and T3 also 439 show the growing of the boundary layer along the train length. In contrast, train T1 exhibits fluctuations 440 between stages of development and significant reduction, with considerably greater symmetric flow. These 441 trends are also visible in the boundary layer displacement thickness profiles in Figure 10, with T2 and T3 442 developing to a larger displacement thickness. As noted in Table 1, and quantified in Figure 11, the loading 443 configuration of T1 contained the larger and more consistent gaps. Therefore, the loading configuration 444 can be attributed as the cause for reduced boundary layer size. The greater symmetry observable for T1 445 is likely attributable to the lower crosswind ($\beta = -0.3$). However, the smaller boundary layer caused 446 by the loading configuration may also result in the flow field being less sensitive to crosswind that is less 447 observable in these results. 448

Inspection of the horizontal velocity component, v, in Figure 19 identifies the initial flow away from the head of the train (x = 0m). The flow then generally tends towards the train surface with a magnitude of $v \approx 0.08u_t$, with relatively incoherent oscillations along the trains. Stronger horizontal flow ($v \approx 0.1u_t$) towards the rail centre occurs after the tail has passed as the wake closes. This is most clearly visible for train T2 in Figure 19b, and highlighted specifically with u, v velocity vectors presented in Figure 23.

454 3.3.2. Local topology

An apparent correlation is evident between the fluctuations in u and v velocity beyond the effect of 455 crosswind already described. This occurs most clearly at x = 400 m and x = 800 m for train T1, where on 456 the positive y side of the train, a large region of flow with an increase in v velocity directed towards the train, 457 corresponds to a decrease in u velocity. The u velocity in the region over x = 400-800 m is presented in 458 Figure 21 and u, v vectors over x = 600-700 m in Figure 22, with the loading configuration also illustrated 459 from the light-gate measurements. In Figures 21 and 23, the turbulent flow field is visualised, with some 460 indications of vortex structures existing in the flow arising from the shear layer interaction between the 461 high velocity induced flow near the train surface and the ambient wind away from the train. However, from 462 these results, a single gap on its own does not have a singular identifiable effect on the flow. It appears that 463 it is the cumulative combination of a series of gaps that results in flow that is analogous to that seen at the 464 tail of the train (Figure 23) and the overall decrease in the bulk induced flow. 465

The vertical velocity component, w, presented in Figure 20 shows regions of fluctuating sign at much 466 smaller scales ($\approx 10-25$ m) than the fluctuations in longitudinal, u velocity (> 100 m). This is evident 467 most clearly for train T3, but also for trains T1, T2 and T4 on the leeward side. These fluctuations are 468 strongest ($w = \pm 0.1 u_t$) closest to the surface, and convect away, lagging behind the point of origin. A 469 possible explanation for such vertical velocity fluctuations and approximate length scales is the formation 470 of horseshoe-type vortices rolling up in front of individual shipping containers with enough of a gap at 471 the front to experience relatively clean flow. Although interesting, these result do not appear to have a 472 significant effect on the overall boundary layer development. 473

The horizontal, v (Figure 19), and vertical, w (Figure 20), velocity components are difficult to interpret 474 for the trains with high-crosswind (T4,T5,T6). The leeward side is expected to exhibit a three-dimensional 475 flow topology, primarily consisting of a semi-longitudinal vortex that develops from separation at the lee-476 ward upper edge (Hemida and Baker, 2010, Copley, 1987). The v and w velocity magnitude and direction 477 measured by the probes in the horizontal array are therefore dependent on the relative height of the structure 478 as it passes through the array. In addition, such a structure is likely unsteady itself, and further influenced 479 by the unsteady crosswind and non-uniform loading configuration. Thus, the v and w velocity figures are 480 inconsistent for the different trains with high crosswinds, and no clear trends or characteristic features are 481 able to be determined. 482



Figure 18: Coloured contours of longitudinal velocity, u/u_t , around trains T1–T6: (a)–(f). The position of each train indicated by a black outlined box.



Figure 19: Coloured contours of horizontal velocity, v/u_t , around trains T1–T6: (a)-(f). The position of each train indicated by a black outlined box.



Figure 20: Coloured contours of vertical velocity, w/u_t , around trains T1–T6: (a)–(f). The position of each train indicated by a black outlined box.



Figure 21: Coloured contours of longitudinal velocity, u/u_t , around train T1 over the section x = 400-800 m with a series of consecutive gaps. Train indicated by black box and gaps by white spaces.



Figure 22: Velocity vectors of u, v, around train T1 over the section x = 600-700 m with a series of consecutive gaps. Train indicated by black box and gaps by white spaces.



Figure 23: Velocity vectors of u, v, around train T1 over the section x = 1450-1700 m, where the train tail is visible. Train indicated by black box and gaps by white spaces.

483 3.4. Frequency analysis

Frequency analysis was performed on the velocity measurements. In Figure 24, the frequency spectra from the seven probes in rake R1 calculated over the middle 40% of train T1 are presented for the different velocity components. The power spectral density was estimated using the Welch method with 8 Hamming windows and 50 % overlap. The results are representative of the low crosswind trains (T1, T2, T3).

A broad frequency band over the range of f = 0.5-5 Hz with various specific peaks at $f \approx 1, 1.5$, 2 and 3 Hz are visible for all three velocity components. This band becomes stronger, closer to the train. Additional higher frequency peaks at $f \approx 22$ Hz and $f \approx 35$ Hz are also visible in the spectra across all of the measurement positions.

⁴⁹² Due to the relative motion between the vehicle, the surrounding induced fluid flow and the measurement ⁴⁹³ probe, it is difficult to separate periodic aerodynamic features (e.g. vortex shedding, as observed by Li et al. ⁴⁹⁴ (2017) in the wake of containers) and periodic features caused by the train moving past the measurement ⁴⁹⁵ equipment (e.g. repetitive passing of individual containers, ribs on the containers, wagons and bogies).

Vortex shedding from the sides of containers, if existent, would correspond to $f \approx 3$ Hz (from an 496 approximate Strouhal number of $St_W \approx 0.2$ based on the container width). Higher frequency shear-layer 497 vortices could also occur with $f \approx 23$ Hz ($St_W \approx 1.5$). Conversely, repetitive signals observed in the 498 light gate measurements with length scales of 17-22 m associated to the wagons and/or containers passing 499 the measurement position, correspond to frequencies of $f \approx 1.4$ –1.75 Hz. Repetitive signals from the 500 container ribs ($x \approx 0.2$ m) correspond to much higher frequencies of $f \approx 150$ Hz. These values are based 501 on the train speed of $u_t = 30$ m/s. However, the boundary layer is also likely to modify the flow conditions 502 such estimations are based on. This could result in a reduced effective velocity, and increased effective 503 widths, and therefore different corresponding expected frequencies. 504

Although minor trends and features in the spectra can be observed, there are no clear dominant frequencies that can be directly attributable to unsteady aerodynamic characteristics. This can be expected for real-world measurements in complex conditions. Regardless of the difficulty in their interpretation, these results are presented as they may be useful for comparison to future wind-tunnel or numerical aerodynamic investigations of freight trains.

510 3.5. Correlation

Analysis of the cross-correlation of the velocity fluctuations between the probes at different positions provides insight into the existence and scale of coherent flow structures. Such analysis is also useful to infer the influence that the loading configuration has on the flow field, in contrast to the ambient wind.



Figure 24: Power spectral density (PSD) determined from Fast Fourier Transform (FFT) of the different velocity components: (a) u, (b) v, (c) w measured by probes P1–P7 from rake R1, taken over the middle %40 section of train T1.

In this section, correlation analysis over the middle 40% section of train T1 is presented for the different velocity components. The results are representative of the low crosswind trains (T1, T2, T3).

In Figure 25, the cross-correlation of probe P1 (closest to the train, y = 1.71 m) with each of the 516 probes (P1-P7) in rake R1 is presented for the u velocity component. As expected, moving away from the 517 train, reducing correlation is visible. The correlation coefficient, ρ , decreases from a relatively high value 518 $(\rho = 0.6)$ over a short distance $(\Delta y = 1 \text{ m})$, to a relatively low value $(\rho = 0.2)$ at the largest distance 519 $(\Delta y = 6 \text{ m})$. Similarly, an increasing time-lag exists moving away from the train before the probes exhibit 520 their highest correlation. This time-lag is perhaps expected for the close probes (e.g. t < 1.7 s for $\Delta y < 4$ 521 m), however, it increases significantly for $\Delta y = 5$ m and $\Delta y = 6$ m, to considerable time-lags of $t \approx 5$ 522 s and ≈ 8 s (corresponding to $x \approx 240$ m) respectively. These findings are supported by the results in 523 Figure 18, where a fluctuation or feature in the velocity close to the train only convects to the furtherest 524 measurement position after a longitudinal length in the range of $x \approx 240$ m. 525

Correlation in the transient flow field either side of the train would indicate the loading configuration 526 has a significant effect on the flow field, as its influence is expected to be symmetric, affecting both sides 527 at the same time. In contrast, cross-wind is expected to reduce symmetric in-phase correlation. Symmetric 528 horizontal correlation was investigated by calculating the cross-correlation between the respective probes 529 in rakes R1 and R2 on either side of the train (e.g. R1, P1 (y = 1.71 m) to R2, P1 (y = -1.71 m)). The 530 results for the u velocity component are presented in Figure 26. The probes close to the train (y = 1.71, 531 2.71, 3.71 m) exhibit reasonably high correlation with each other ($\rho \approx 0.4$). However, the two probes at 532 y = 2.71 and 3.71 m exhibit the highest correlation for a time-lag of ± 1 s, indicating that already at these 533 distances, the ambient crosswind may be skewing the flow. Negligible correlation was apparent for the v534 and w velocity components for either the symmetric or one-sided horizontal correlation analysis. 535

Longitudinal correlation was analysed using the measurements made at the different rakes (R1, R3,

⁵³⁷ R4) on the same side (+y) of the train. This enabled two cases with $\Delta x = 15$ m (R1–R2, R3–R4) and one ⁵³⁸ case of $\Delta x = 30$ m (R1–R4) to be analysed. The autocorrelation of R1 probes with themselves were also ⁵³⁹ calculated, and all cases are presented in Figure 27 for the four horizontal probe positions closest to the ⁵⁴⁰ train. The *u* component of velocity is only presented here, as the *v* and *w* components exhibited negligible ⁵⁴¹ correlation.

If the flow field around the train were steady over time, high levels of correlation would exist with 542 time-lags corresponding to their distances relative to each other at the test-site divided by the train velocity 543 $(t = \Delta x/u_t = 0.5 \& 1 \text{ s when } \Delta x = 15 \& 30 \text{ m}$, respectively). However, this is not observed in the 544 results. Distinct peaks in correlation coefficient of $\rho \approx 0.4$ are visible for both longitudinal distances; 545 however, they are not consistent across the different horizontal positions. In spite of this inconsistency, a 546 trend is visible of increasing time-lag moving away from the train in the horizontal direction. Even at the 547 closest position, y = 1.71 m, the time-lag of ≈ 1 s is greater than the estimated lag of 0.5 s using distance 548 and train speed. This increasing time-lag indicates that transient flow structures are generated at the train 549 and then convect away with reducing velocity. The remaining velocity fluctuations not contributing to the 550 $\rho \approx 0.4$ correlated flow could be attributed to additional transient features in the flow, as well as the effect 551 of transient crosswinds. 552



Figure 25: Cross correlation of the longitudinal velocity, u, measured over the middle 40% section of train T1 by each probe (P1–P7) in the horizontal rake R1, with P1, presented in terms of the correlation coefficient, ρ .



Figure 26: Cross correlation of the longitudinal velocity, u, measured over the middle 40% section of train T1 by each probe (P1–P7) in the horizontal rake R1 (+y) to its corresponding probe (P1-P7) on the other side of the train in rake R2 (-y).



Figure 27: Cross correlation of the longitudinal velocity, u, measured over the middle 40% section of train T1 over different longitudinal distances: $\Delta x = 0m$ (R1–R1), $\Delta x = 15m$ (R1–R3, R3–R4), $\Delta x = 30m$ (R1–R4), from different corresponding probes. (a) P1 (y = 1.71 m) and (b) P3 (y = 1.71 m) in each of the different rakes: R1, R3, R4, on the same side of the train (+y).

553 4. Conclusions

The boundary layers that develop on the sides of full-scale operational inter-model freight trains have been measured at a test-site set-up situated around a single standard-gauge rail in Victoria, Australia. Rakes of 4-hole dynamic-pressure probes were utilised to measure the velocity induced by passing trains, enabling calculation of the boundary layer characteristics, as well as providing insight into the transient flow topology around a set of six trains.

The characteristic boundary layer – an average boundary layer that occurs at the approximate middle of freight trains operating within low ambient wind ($\beta < 2^{\circ}$) – was determined to have: a displacement thickness of $\delta^* = 1.6$ m (within a range of $\delta^* = 0.5$ –3 m), a turbulence intensity profile ranging from 4– 13% with relatively consistent anisotropy ratios of $I_u : I_v : I_w \approx 1 : 0.4 : 0.6$, and turbulent length-scales in the range 5–30 m. This characteristic boundary layer and its additional salient features are illustrated in Figure 28; it is intended to help inform future experiments and simulations, in order to model real-world conditions experienced by moving freight trains.



Figure 28: Salient features of the characteristic boundary layer around an operational inter-modal freight train.

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Even relatively low ambient-wind conditions (with relative yaw angles $\beta < 2^{\circ}$) were observed to have an effect on the boundary layer and flow topology at the two sides of a train. Measurements taken either side of the trains exhibited differences in the calculated displacement thickness – and corresponding agreement for multiple measurements taken on the same side of the train - as well as visible asymmetry in the flow topology. These results are not expected to be caused by the loading configuration of the vehicles, and thus can be attributed to the (albeit weak) mean and fluctuating components of the ambient wind.

Loading configuration was found to only have a noticeable influence on the displacement thickness 572 and flow topology when a series of consecutive gaps (> 2 m) between shipping containers existed. This 573 loading configuration led to a reduction in displacement thickness and the bulk induced flow around the 574 train, as one would expect. A measure of the cumulative blockage of the trains was shown to be useful 575 in visualising the loading configuration and exhibited the same trends in the large-scale variation of the 576 displacement thickness profile along the freight trains. No single gap, in spite of significant sizes (> 10 m), 577 was observed to have an observable/measurable effect on either the flow field or displacement thickness, 578 at least in the measurement region away from the train side surfaces. (The first probe was located at 1.7 m 579 from the train of width 2.1 m). 580

The rakes of 7 probes either side of the train provided some insight into transient flow field around the 581 train. Following rapid development of the boundary layer over the first 200 m, the average flow field at 582 the middle of the trains exhibited longitudinal velocities of $u = 0.4u_t$ (40% of the train speed) and flow 583 towards the train surface of $v = 0.1u_t$ at y = 1.71 m from the surface, reducing to $u = 0.1u_t$ & $v = 0.02u_t$ 584 respectively at y = 7.71 m away from the surface. Fluctuations in longitudinal velocity, caused by large-585 scale turbulent structures were observed to convect away with reducing velocity from the train surface 586 and downstream. This was evident in the velocity coloured contours and identified in the horizontal and 587 longitudinal correlation analysis. Further, the transient flow was seen to be somewhat correlated either side 588 of the train, with maximum correlation coefficients of $\rho = 0.4$ recorded closest to the train ($\pm y = 1.71$ m) 589 reducing to $\rho = 0$ away from the train ($\pm y = 7.71$ m). This symmetric horizontal correlation is expected to 590 be caused by the loading configuration influencing the flow topology. Frequency analysis was performed, 591 however clear dominant frequencies were not evident, with the results being difficult to interpret due to the 592 relative motion of the experiment. 593

⁵⁹⁴ Higher crosswinds ($\beta = 4-10^{\circ}$) resulted in the flow field on the windward side of the train being pushed ⁵⁹⁵ close to the surface beyond the reach of the measurement equipment. On the leeward side of the train, signs ⁵⁹⁶ of the three-dimensional flow field consisting of system of longitudinal vortices forming from separation at ⁵⁹⁷ the trailing edges of the train and containers were observed, but it was not possible to clearly characterise ⁵⁹⁸ these due to their complexity and lack of measurement resolution. This resulted in significantly larger ⁵⁹⁹ bulk induced flow on the leeward side of the train with larger velocities than observed in low crosswind ⁶⁰⁰ conditions.

The findings presented from this novel experiment: characterising and quantifying the boundary layer structure, and providing insight into the transient flow topology around freight trains, together provide aerodynamic characteristics of typical inter-modal freight trains operating in open air under low crosswind 604 conditions.

The sample size of six trains is acknowledged to be relatively small, even considering that each train 605 is effectively measured three times by each of the horizontal boundary-layer rakes. However, these are the 606 first measurements attempting to spatially and temporally resolve the boundary layers of freight trains op-607 erating in real-world conditions. The corresponding results provide (even with variation between different 608 trains as well as along each train's length) an indication of boundary-layer characteristics representative of 609 real-world freight trains that are significantly different than what is typically modelled in wind-tunnel and 610 numerical simulations. These results provide valuable insight that can be useful for comparative aerody-611 namic investigations on inter-modal freight train aerodynamics in the future. 612

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